

#### **Background & Problem Statement**

In 2009, the Abaarso School for Science and Technology was founded as a not-for-profit private school in Abaarso, Somaliland. The school currently relies on trucks to deliver water to tanks inside the campus. Further, they have no pump to increase water pressure; they rely on gravity for water flow.

The Abaarso school requires a digitized and automated water distribution system to ensure students and faculty have direct and easy access to water.



#### **Customer Requirements**

- Automatically refill tanks when low
- Durable and reliable; able to run 10+ years
- Detect water loss due to leaks
- User-friendly manual overrides

#### **Future Work**

- > Integrate flow meter hardware and software to detect leaks in the system.
- > Determine the cost of the full-scale water system to be constructed at the Abaarso School.
- > Begin preliminary designs for the full-scale water distribution system. Start discussions with experts.

## **Smart Water Distribution Model**

#### **Team Mango Tango**

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#### Hardware: Sensors & Devices



Level switch (Input): detects high and low tank water levels

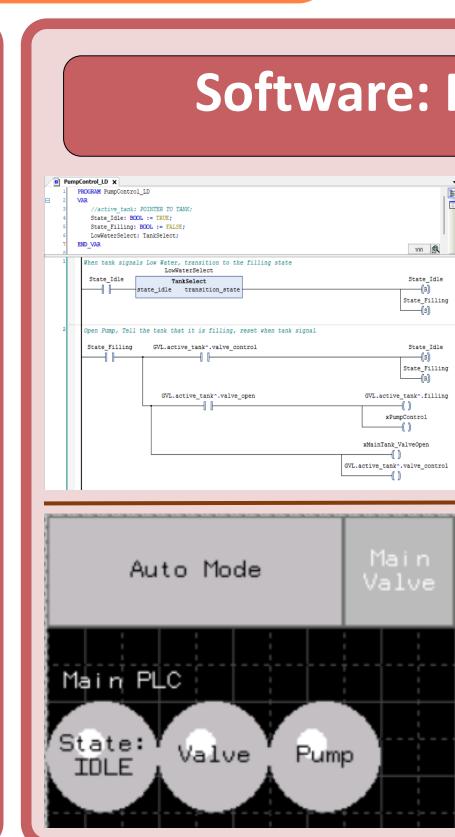


Flow meter (Input): measures flow rate of water in mL/s

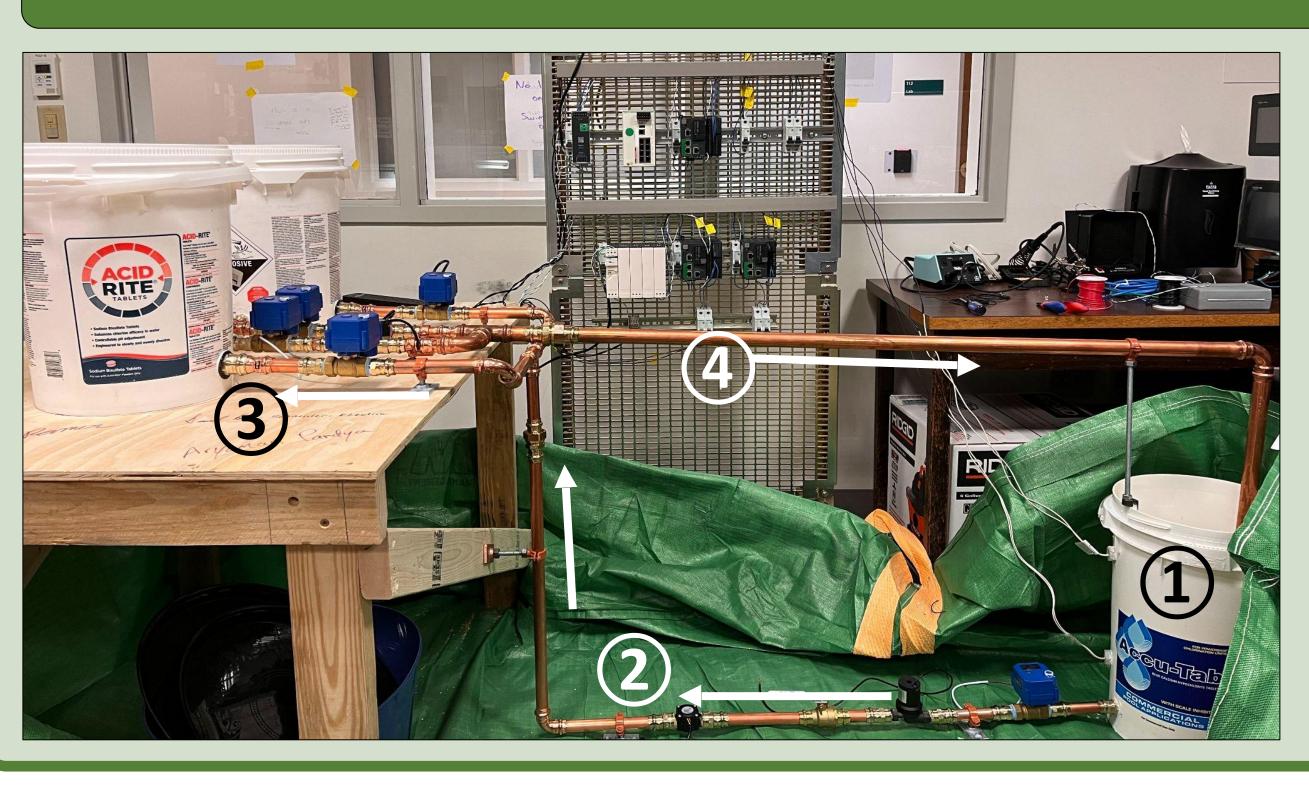


Valve (Output): opens and closes to allow water flow

Pump (Output): Initiates flow of water



### The Lab Model



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# Schneider Electric

#### **Software: PLCs & User Interface**

D X			
PumpControl_LD tive_tank: POIN e_Idle: BOOL := e_Filling: BOON aterSelect: Tar	= TRUE; L := FALSE;		100
ank signals Low Water, transition to the filling state LowWaterSelect			
e_Idle	TankSelect e_idle transition_state		State_Idle ([R]) State_Filling ([S])
Filling	<pre>tank that it is filling, r GVL.active_tank^.valve_con GVL.active_tank^.valve_c </pre>	trol	State_Idle ([5]) State_Filling ([7]) GVL.active_tank^,filling ([)) xPumpControl ([)) xMainTank_ValveOpen ([)) GVL.active_tank^,valve_control ([))

**Programmable Logic Controller:** PLC programs communicate with each other and control water distribution. Programmed in Ladder Logic.

**User Interface:** Displays status of sensors & devices, and allows manual control of the hardware if necessary.

- 1. Water starts in the grounded bucket.
- 1. If elevated buckets are low on water, pump turns on, entry valves open, and elevated buckets begin filling. Water flows left and vertically upwards.
- 1. Once the elevated buckets are filled, the pump turns off and entry valves close.
- 1. Finally, exit valves open and water drains back into the grounded bucket. Perpetual motion of water is achieved.