

Background & Problem Statement

In 2009, the Abaarso School for Science and Technology was founded as a not-for-profit private school in Abaarso, Somaliland. The school currently relies on trucks to deliver water to tanks inside the campus. Further, they have no pump to increase water pressure; they rely on gravity for water flow.

The Abaarso school requires a digitized and automated water distribution system to ensure students and faculty have direct and easy access to water.



Customer Requirements

- Automatically refill tanks when low
- Durable and reliable; able to run 10+ years
- Detect water loss due to leaks
- User-friendly manual overrides

Future Work

- > Integrate flow meter hardware and software to detect leaks in the system.
- > Determine the cost of the full-scale water system to be constructed at the Abaarso School.
- > Begin preliminary designs for the full-scale water distribution system. Start discussions with experts.

Smart Water Distribution Model

Team Mango Tango

By Max Ramer, Sinan Unan, Aryaman Pandya, Ethan Schreiber

Hardware: Sensors & Devices



Level switch (Input): detects high and low tank water levels

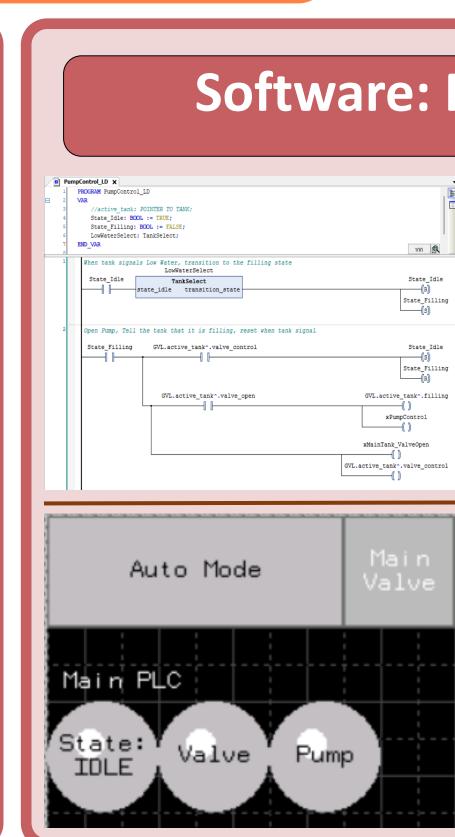


Flow meter (Input): measures flow rate of water in mL/s

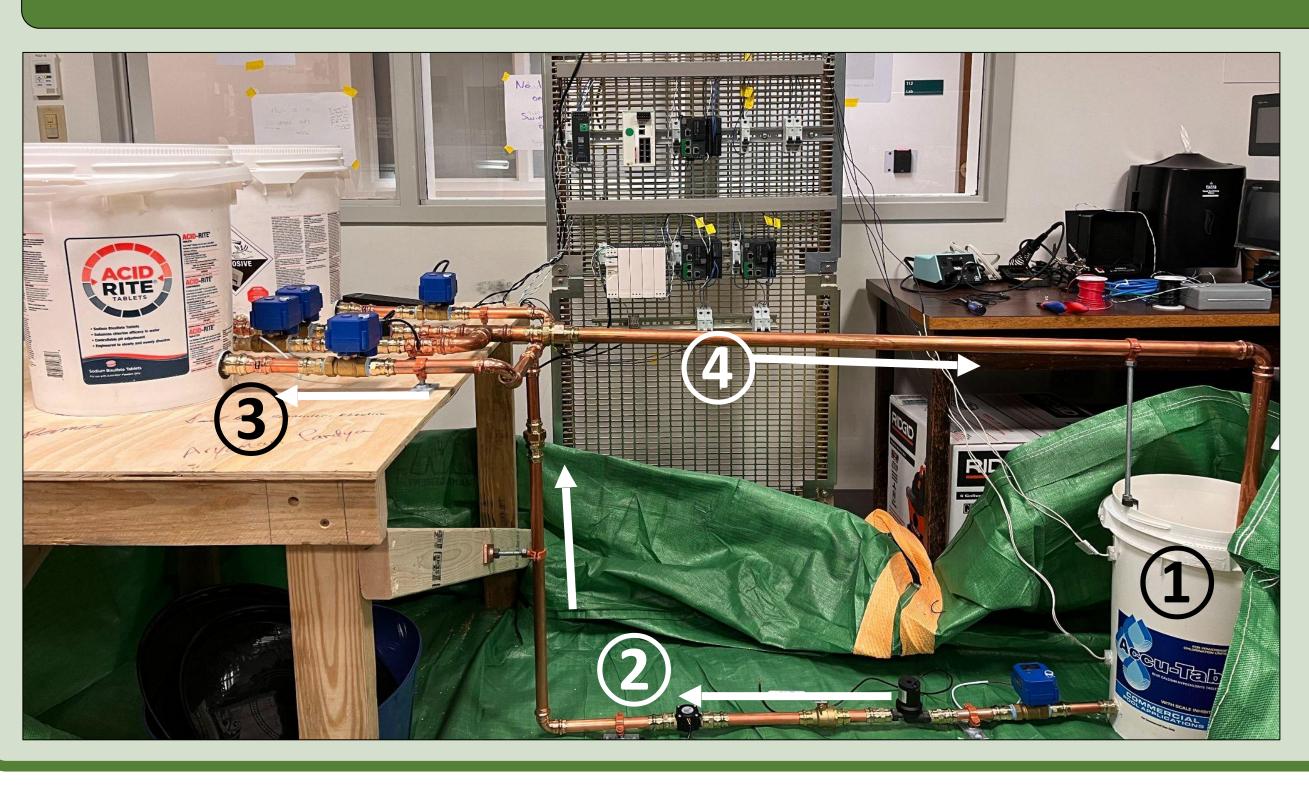


Valve (Output): opens and closes to allow water flow

Pump (Output): Initiates flow of water



The Lab Model



Acknowledgements: Deepest gratitude goes to our sponsor Schneider Electric for the opportunity to work on this project. Special thanks to Suad Morgan, Behnaz Champey, Louis Arone, Don Dube, and Herb Read for consistently going the extra mile. Additional thanks to the Tufts ECE department: Professors Ron Lasser and Dave Lillethun, and Miriam Santi and CJ Cassidy in the ECE office.



Schneider Electric

Software: PLCs & User Interface

D X			
PumpControl_LD tive_tank: POIN e_Idle: BOOL := e_Filling: BOON aterSelect: Tar	= TRUE; L := FALSE;		100
ank signals Low Water, transition to the filling state LowWaterSelect			
e_Idle	TankSelect e_idle transition_state		State_Idle ([R]) State_Filling ([S])
Filling	<pre>tank that it is filling, r GVL.active_tank^.valve_con GVL.active_tank^.valve_c </pre>	trol	State_Idle ([5]) State_Filling ([7]) GVL.active_tank^,filling ([)) xPumpControl ([)) xMainTank_ValveOpen ([)) GVL.active_tank^,valve_control ([))

Programmable Logic Controller: PLC programs communicate with each other and control water distribution. Programmed in Ladder Logic.

User Interface: Displays status of sensors & devices, and allows manual control of the hardware if necessary.

- 1. Water starts in the grounded bucket.
- 1. If elevated buckets are low on water, pump turns on, entry valves open, and elevated buckets begin filling. Water flows left and vertically upwards.
- 1. Once the elevated buckets are filled, the pump turns off and entry valves close.
- 1. Finally, exit valves open and water drains back into the grounded bucket. Perpetual motion of water is achieved.