







Arduino can be connected to different input and output devices

Sensors or buttons can be used to generate an output effect:

Ex: A push button can be pressed to turn on a light or a servo motor to spin a small fan.



Arduino Uno's can convert analog to digital signals

- Digital signals have only two values, HIGH and LOW.
- Analog signals can take on any number of values.
- Think of Analog like a dimmer switch while Digital is a light switch.

There are many different types of Arduino microcontrollers that each have their own use.











Coding in Arduino is done in Arduino "sketches" in the Arduino IDE*



- A Sketch is composed of 3 components
 - Global Variable which are declared at the top
 - Here you define variables and libraries you want to use
 - Setup() is the initialization code you wish you run at the start of the code, this is also where you defines Pins and notify the Arduino where things are connected
 - The last part is the Loop(). This is where you list your functions that you want to run continuously.

*IDE: Integrated Development Environment



Download Software <u>https://www.arduino.cc</u> → software

https://www.arduino.cc/en/software

Simple Exercise: BLINK

Step 0: Load Blink Example

	•		New	жN		👦 Blink	Arduino IDE	2.0.0
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_	Blink.ino		Examples	>	Bu	ilt-in examples		
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	26	v	Save	жs	02	2.Digital	>	BareMinimum
]	27		Save As	ሪ	03	3.Analog	>	Blink
	28	2	•		04	I.Communication	>	DigitalReadSerial
1	30	,			05	5.Control	>	Fade
Ц	31	11	the loop	function r	ur 06	S.Sensors	>	ReadAnalogVoltage
	32	vo	oid loop()	{	07	Display	>	
>	33		digitalWr	<pre>ite(LED_BUI)</pre>	L1 08	B.Strings	>	GH is the voltage level)

Blink Step 1: Check the correct board and serial port are selected in the tools menu

			Auto Format	ЖТ	
			Archive Sketch		Jino IDE 2.0.0
		Į.	Manage Libraries	ሰ	
		1 .	Serial Monitor	ŵЖМ	
P	Blink.inc)	Serial Plotter		
	25	// tne			t or power the board
	26	void <mark>se</mark>	Board: "Arduino Uno"	>	
<u>•</u>	27	// in	Port: "/dev/cu.usbmodem101"	>	Serial ports
	28	pinMo	Get Board Info		✓ /dev/cu.usbmodem101 (Arduino Uno)
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Ш	31	// the	WIFITOT / WIFININA FITTIWATE Opuater		/dev/cu.OpenMovebyShokz
	32	void lo	Upload SSL Root Certificates		/dev/cu.Bluetooth-Incoming-Port
T A	> 33	digit	Programmer	>	D on (HIGH IS THE VOLTAGE LEVEL)
X.	34	delav			econd

Blink Step 2: Verify & Upload the program



 Change the values of delay() to see how it affects the behavior

CLASS EXERCISE: ULTRASONIC SENSOR

Determine proximity, Add LED light



Ultrasonic Sensor HC-SR04

Operating Voltage	5V DC
Operating Current	15mA
Operating Frequency	40KHz
Min Range	2cm / 1 inch
Max Range	400cm / 13 feet
Accuracy	3mm
Measuring Angle	<15°
Dimension	45 x 20 x 15mm



The sensor has 4 pins. *VCC* and *GND* go to *5V* and *GND* pins on the Arduino, and the *Trig* and *Echo* go to any digital Arduino pin. Using the *Trig* pin we send the ultrasound wave from the transmitter, and with the *Echo* pin we listen for the reflected signal.



The time between the transmission and reception of the signal allows the calculation of the distance to an object. We know the sound's velocity in the air: distance to an object = ((speed of sound in the air)*time)/2 speed of sound in the air ~**340m/s**



Ultrasonic Sensor HC-SR04	Arduino
VCC	5V
Trig	Pin 11
Echo	Pin 12
GND	GND

Best practiceImage: "the set of the set of

Then wire to Arduino

```
int trigPin = 11; // Trigger
int echoPin = 12; // Echo
float duration, cm, inches; //for number
storage, 6-7 decimal precision
```

- create variables for the trigger and echo pin called trigPin connected to Pin 11 and echoPin to Pin 12
- three variables of type float: duration, cm and inches. The duration variable saves the time between the emission and reception of the signal. The cm variable will save the distance in centimeters, and the inches variable will save the distance in inches
- Float has 6-7 digit decimal precision

```
void setup() {
Serial.begin (9600); // initialize serial
port
pinMode(trigPin, OUTPUT); //set arduino
pin to output mode
pinMode(echoPin, INPUT); //set arduino pin
to input mode
}
```

 initialize the serial port at a baud rate of 9600, and set the trigger pin as an OUTPUT and the echo pin as an INPUT

void loop() {
 // generate 10-microsecond pulse to
 trigPin
 digitalWrite(trigPin, HIGH);
 delayMicroseconds(10);
 digitalWrite(trigPin, LOW);
 // measure the duration of pulse from
 echoPin
 duration = pulseIn(echoPin, HIGH);
 // Convert the time into a distance
 cm = (duration/2) / 29.1; // Divide by
 29.1 or multiply by 0.0343
 inches = (duration/2) / 74; // Divide
 by 74 or multiply by 0.0135

- Trigger the sensor by sending a HIGH pulse of 10 microseconds.
- Use the pulseIn () function to get the sound wave travel time
- The pulseIn() function reads a HIGH or a LOW pulse on a pin. It accepts as arguments the pin and the state of the pulse (either HIGH or LOW). It returns the length of the pulse in microseconds. The pulse length corresponds to the time it took to travel to the object plus the time traveled on the way back
- Calculate the distance to an object, taking into account the sound speed.
 - distance = (traveltime/2) x speed of sound The speed of sound is: 343m/s = 0.0343 cm/uS = 1/29.1 cm/uS Or in inches: 13503.9in/s = 0.0135in/uS = 1/74in/uS

```
    Print the results in the Serial Monitor
```

// print value to Serial Monitor

```
Serial.print(inches);
Serial.print("in, ");
Serial.print(cm);
Serial.print("cm");
Serial.println();
delay(250);
}
```



Now Add LED

LED to turn on when object moves close LED to turn off when object moves away

LED includes two pins:





Long leg on LED is anode (+) and connects to power.

Short leg on LED is cathode (-) and connects to ground

Resistor Information

Resistor Color Code Chart

The chart below shows how to determine the resistance and tolerance for resistors. The table can also be used to specify the color of the bands when the values are known. An automatic resistor calculator can be used to quickly find the resistor values.



- The reading direction might not always be clear. Sometimes the increased space between bands 3 and 4 provide an indication of the reading direction. Also, the first band is usually the closest to a lead. A gold or silver band (the tolerance) is always the last band.
- It is a good practice to check the manufacturer's documentation to be sure about the color coding system used.
- When in doubt, measure the resistance with a ohmmeter. In some cases this might even be the only way to figure out the resistance; for example when the color bands are burnt off.

https://eepower.com/resistor-guide/resistor-standards-and-codes/resistor-color-code/#



```
What do you need to add to your code?
```

```
int distance_threshold = 15; // Centimeters
```

```
pinMode (5, OUTPUT); //set LED pin to output mode
```

```
if (cm < distance_threshold)
digitalWrite (LEDPin, HIGH); //Turn on LED
else
digitalWrite (LEDPin, LOW); //Turn off LED</pre>
```



CLASS EXERCISE: TEMPERATURE & HUMIDITY SENSOR, LEDS

Determine temperature and humidity, LED lights depending on temperature

Step 1: Make sure your board is detected by going to Tools-> Port-> Arduino Uno



Step 2: Open the DHT_uncommented.ino sketch from canvas



Step 2b: Download the DHT sensor library(Sketch-> Include Library-> Manage Libraries)

🙄 DHTt	ester Arduino 1.8.13 (Windows St	ore 1.8.42.0)	$ \Box$ >
File Edit	Sketch Tools Help		
00	Verify/Compile	Ctrl+R	ø
	Upload	Ctrl+U	
DHTte	Upload Using Programmer	Ctrl+Shift+U	
	Export compiled Binary	Ctrl+Alt+S	
#includ	Show Sketch Folder	Ctrl+K	Manage Libraries
#define	Include Library	;	
// Feat	Add File		Add .ZIP Library
// Uncou //#defin #define //#defin	nment whatever type you're ne DHTIYPE DHT11 // DHT DHTIYPE DHT22 // DHT 22 ne DHTIYPE DHT21 // DHT ect pin 1 (on the left) of I ferrier a band with 2	Arduino libraries Bridge EEPROM Esplora Ethernet Firmata	
// to 3	.3V instead of 5V!	GSM	
<pre>// Connect pin 2 of the sensor to whatever y // Connect pin 4 (on the right) of the senso // Connect a LOW resistor from pin 2 (deta)</pre>			HID
			Keyboard
,,, oom	too u ton tebibbot tiom pi		LiquidCrystal
<			Mouse
			Robot Control
			Robot IR Remote
			Robot Motor
			SD
			SPI
1			Servo

Step 2c: Search latest version	n for DHT and install the
	Type: All 🗸
	Topic: All ✓ nret="nttps://www.dtrobot.cor 3282.html">https://www.dtrob 3282.html Provide an Arduino library to get Humidity and
	DHT sensor library by Adafruit Version 1.4.4 INSTALLED Arduino library for DHT11, DHT22, etc Temp & Humidity Sensors Arduino library for DHT11, DHT22, etc Temp & Humidity Sensors More info

DHT11 Humidity And Temperature Sensor

- Measures water vapor by measuring the electrical resistance between two electrodes.
 - Change in resistance between the electrodes is proportional to RH
 - Higher (lower) RH decreases (decreases) the resistance between the electrodes
- Measures temperature with surface mounted NTC temperature sensor (thermistor)

$$RH = \left(\frac{\rho_w}{\rho_s}\right) x \ 100\%$$

RH: Relative Humidity ρ_w : Density of water vapor

 ρ_s : Density of water vapor at saturation

DHT11 Humidity And Temperature Sensor

- Uses 1 signal wire to transmit data to the Arduino
- Power from separate 5v and Ground
- 10K Ohm resistor needed between signal and 5V(Vcc) to make sure signal level stays high





*sensor datasheets will tell you this information

Step 3: Wiring Our Temperature and Humidity Sensor



- Connect the left most pin to Digital pin 2
- Connect a 10k resistor from the left most pin to center pin
- Connect the center pin to the 5V track
- Connect the right most pin to the ground track.

Step 4: Confirm Everything is Working

- Make sure you Port is selected
- Verify
- Upload
- Open Serial Monitor
- Read Temperature and Humidity
- What happens if you blow air onto the sensor?





Resistor Information

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https://eepower.com/resistor-guide/resistor-standards-and-codes/resistor-color-code/#

Step 6: Lets comment our code and upload it

	void loop() {
	detay(500);
	Ttoat n = ant.readHumidity(); // collect numidity measurements after Sooms
	<pre>float t = dht.readTemperature(); //collect degrees celsius</pre>
<pre>#include "DHT.h"</pre>	
	<pre>float f = dht.readTemperature(true); // collect degrees fahrenheit</pre>
#define DHTPIN 2 // Set the Temperature sensor pin	<pre>Serial.print(("Temperature is "));</pre>
,, out the remperature concer pair	<pre>Serial.print(f);</pre>
#define DHTTYDE DHT11 // Define sensor type	<pre>Serial.println(("°F ")); // Print temperature on serial monitor</pre>
#define Diffire Diffie // Define Sensor type	if (isnan(h) isnan(t) isnan(f)) { //Catches errors during DHT collection
	<pre>Serial.println(E("Failed to read from DHT sensor!")):</pre>
DHI dht(DHIPIN, DHIIYPE);	return:
	1 County
<pre>void setup() {</pre>	I
<pre>Serial.begin(9600); // Start a serial monitor section</pre>	1 (1 > 74) (7) If degree randemetric is above 74, turn of green tryit, otherwise, turn on red tryit
<pre>Serial.println("Testing Temp"); // Initialization of serial monitor</pre>	digitatwrite(12, nich);
<pre>pinMode(12,0UTPUT); // Define Red LED output pin</pre>	digita(Write(13,LOW);
<pre>pinMode(13.0UTPUT): // Define Green LED output pin</pre>	} else {
<pre>dht.begin(): // Start the DHT sensor</pre>	<pre>digitalWrite(13,HIGH);</pre>
	<pre>digitalWrite(12,LOW);</pre>
,	
	<pre>delay(1500); //wait 1.5 seconds</pre>
	}
	}

💿 DHTtester Arduino 1.8.13 (Wir	ndows Store 1.8.42.0) —	
File Edit Sketch Tools Help		
New Ctrl+N	A	P
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Sketchbook	03.Analog	> ^
Examples >	04.Communication	>
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Save As Ctrl+Shift+S	07.Display	>gram up]
Dana Catura - Chila Chiffe D	08.Strings	>
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Preferences Ctrl+Comma	11.ArduinoISP	>
Quit Ctrl+Q	Examples for any board	
// to 3 3V instead of 5V!	Adafruit Circuit Playground	> Due conr
// Connect pin 2 of the se	Bridge	>
// Connect pin 4 (on the r	Esplora	>
<pre>// Connect a 10K resistor</pre>	Ethernet	,r) of th
	Firmata	> ~
<	GSM	> *
	LiquidCrystal	>
	Robot Control	>
	Robot Motor	>
	SD	>
1	Servo	> on COM4

Where to get started on your own assignment

- Look at examples that come with every library
- Look at the Arduino community page to find new ideas
- Make something interesting by combining the sensors you have



Resources

- <u>Circuitio.io</u>
- <u>https://www.arduino.cc/en/Tutorial/HomeP</u> age
- https://ladyada.net/learn/arduino/
- https://www.circuitbasics.com/arduino/
- https://create.arduino.cc/projecthub/
- https://www.arduino.cc/en/Guide
- <u>https://arduinogetstarted.com/</u>

Electronics

- <u>http://hyperphysics.phy-astr.gsu.edu/hbase/electric/ecircon.html</u> Covers the basics of electric circuits (Ohm's Law, power formulas, basic circuit symbols & design)
- <u>https://app.knovel.com/web/view/khtml/show.v/rcid:kpBSAE0006/cid</u> :kt007RK1G3/viewerType:khtml//root_slug:6electronics/url_slug:electronics?kpromoter=marc&b-toccid=kpBSAE0006&b-toc-root-slug=&b-toc-url-slug=electronics&b-toctitle=Building%20Scientific%20Apparatus%20(4th%20Edition)&page= 25&view=collapsed&zoom=1

Electronics chapter from "Building Scientific Apparatus"generally a great resource for lab research that's available electronically at Tisch. It goes well beyond the scope of BME66 but covers a lot of practical aspects as well (e.g., how to read the stripes on resistors, or how to connect the wire leads of an LED lamp).